

s --> np, vp.

np --> det, n.

vp --> v, np.

vp --> v.

det --> [the].

det --> [a].

n --> [woman].

n --> [man].

v --> [shoots].

**Suppose we wanted to deal with sentences like
``She shoots him", and ``He shoots her". What
should we do?**

pro --> [he].

s([she,shoots,him],[]).

pro --> [she].

yes

pro --> [him].

pro --> [her].

s([a,woman,shoots,she],[]).

yes

np--> pro.

s([her,shoots,a,man],[]).

yes

s([her,shoots,she],[]).

yes

Using extra arguments

s --> np(subject), vp.

np(_) --> det, n.

np(X) --> pro(X).

vp --> v, np(object).

vp --> v.

det --> [the].

det --> [a].

n --> [woman].

n --> [man].

v --> [shoots].

pro(subject) --> [he].

pro(subject) --> [she].

pro(object) --> [him].

pro(object) --> [her].

Checking the coverage

You can check it out by posing the query:

?- s (X, []) .

As you step through the responses, you'll see that only acceptable English is generated.

Syntactic 'sugar'

s --> np, vp .

is really syntactic sugar for

**s (A, B) :-
 np (A, C) ,
 vp (C, B) .**

Using extra arguments

Ok, so we obviously need to ask what

s --> np(subject), vp.

translates into. Here's the answer:

```
s(A, B) :-  
    np(subject, A, C),  
    vp(C, B) .
```

Extra arguments

np (A, B, C) :-
 det (B, D) ,
 n (D, C) .

np (A, B, C) :-
 pro (A, B, C) .

Using a DCG to build parse trees

s (s (NP , VP)) --> np (NP) , vp (VP) .

np (np (DET , N)) --> det (DET) , n (N) .

vp (vp (V , NP)) --> v (V) , np (NP) .

vp (vp (V)) --> v (V) .

det (det (the)) --> [the] .

det (det (a)) --> [a] .

n (n (woman)) --> [woman] .

n (n (man)) --> [man] .

v (v (shoots)) --> [shoots] .

To parse the sentence ``A woman shoots''
we pose the query:

$s(T, [a, woman, shoots], [])$.

That is, we ask for the extra argument T to
be instantiated to a parse tree for the
sentence. And we get:

$T = s(np(det(a), n(woman)), vp(v(shoots)))$

Can we now build semantics
representations?